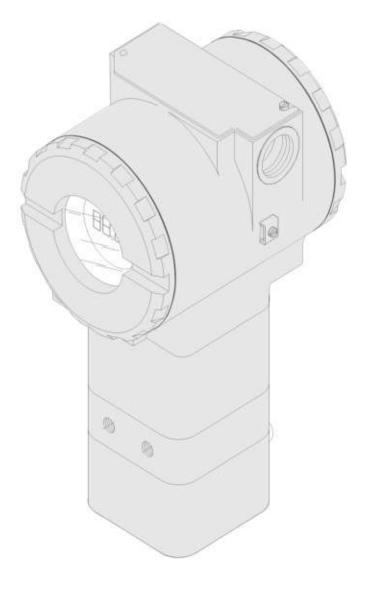


OPERATION AND MAINTENANCE INSTRUCTION MANUAL

# POSITION TRANSMITTER 4 to 20 mA







Specificatinos and information are subject to change without notice. Up-to-date address information is available on our website.

web: www.smar.com/contactus.asp

# INTRODUCTION

The TP290 is from the well-know family of SMAR's devices. It is a transmitter for position measurements. It can measure displacement or movement of rotary or linear type. The digital technology provide an easy interface between the field and control room and several interesting features that considerably reduce the installation, operation and maintenance costs.

The TP290 is versatile and reliable, and has very high accuracy. It may be used for control valve stem position measurement, or in any other position sensing application such as louvers, dampers, crushers, etc.

The TP290 is very versatile, users can standardize one position indicator for all different kinds of control valves and other machines, keeping spares and training to a minimum.

The TP290, besides the normal function of position measurement and 4-20mA output generation, offers the following functions:

- ✓ Linear or Rotary Travel type;
- ✓ 0.1% F.S.;

✓ Position Calibration (4 and 20 mA points) via Local Adjustment or Remote Calibration via Hand Held Terminal;

- ✓ Non contact position sensing;
- ✓ Optional LCD indicator;
- ✓ Diagnostics and Configuration via adjust local.

Get the best results of the TP290 by carefully reading these instructions.

#### NOTE

This manual is compatible with version 1.XX, where 1 denotes software version and XX software release. The indication 1.XX means that this manual is compatible with any release of software version 1.

#### Waiver of responsibility

The contents of this manual abides by the hardware and software used on the current equipment version. Eventually there may occur divergencies between this manual and the equipment. The information from this document are periodically reviewed and the necessary or identified corrections will be included in the following editions. Suggestions for their improvement are welcome.

#### Warning

For more objectivity and clarity, this manual does not contain all the detailed information on the product and, in addition, it does not cover every possible mounting, operation or maintenance cases.

Before installing and utilizing the equipment, check if the model of the acquired equipment complies with the technical requirements for the application. This checking is the user's responsibility.

If the user needs more information, or on the event of specific problems not specified or treated in this manual, the information should be sought from Smar. Furthermore, the user recognizes that the contents of this manual by no means modify past or present agreements, confirmation or judicial relationship, in whole or in part.

All of Smar's obligation result from the purchasing agreement signed between the parties, which includes the complete and sole valid warranty term. Contractual clauses related to the warranty are not limited nor extended by virtue of the technical information contained in this manual.

Only qualified personnel are allowed to participate in the activities of mounting, electrical connection, startup and maintenance of the equipment. Qualified personnel are understood to be the persons familiar with the mounting, electrical connection, startup and operation of the equipment or other similar apparatus that are technically fit for their work. Smar provides specific training to instruct and qualify such professionals. However, each country must comply with the local safety procedures, legal provisions and regulations for the mounting and operation of electrical installations, as well as with the laws and regulations on classified areas, such as intrinsic safety, explosion proof, increased safety and instrumented safety systems, among others.

The user is responsible for the incorrect or inadequate handling of equipments run with pneumatic or hydraulic pressure or, still, subject to corrosive, aggressive or combustible products, since their utilization may cause severe bodily harm and/or material damages.

The field equipment referred to in this manual, when acquired for classified or hazardous areas, has its certification void when having its parts replaced or interchanged without functional and approval tests by Smar or any of Smar authorized dealers, which are the competent companies for certifying that the equipment in its entirety meets the applicable standards and regulations. The same is true when converting the equipment of a communication protocol to another. In this case, it is necessary sending the equipment to Smar or any of its authorized dealer. Moreover, the certificates are different and the user is responsible for their correct use.

Always respect the instructions provided in the Manual. Smar is not responsible for any losses and/or damages resulting from the inadequate use of its equipments. It is the user's responsibility to know and apply the safety practices in his country.

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## **INSTALLATION**

### General

NOTE

NOTE

The installation carried out in hazardous areas should follow the recommendations of the IEC60079-14 standard.

See appendix "A" Hazardous Area Certifications.

The overall accuracy of measurement and control depends on several variables. Although the converter has an outstanding performance, proper installation is essential, in order to maximize its performance.

Among all factors, which may affect converter accuracy environmental conditions are the most difficult to control. There are, however, ways of reducing the effects of temperature, humidity and vibration.

In warm environments, the transmitter should be installed to avoid, as much as possible, direct exposure to the sun. Installation close to lines and vessels subjected to high temperatures should also be avoided. Use of sun shades or heat shields to protect the transmitter from external heat sources should be considered, if necessary.

Humidity is fatal to electronic circuits. In areas subjected to high relative humidity, the o-rings for the electronics cover must be correctly placed. Removal of the electronics cover in the field should be reduced to the minimum necessary, since each time it is re-moved, the circuits are exposed to the humidity.

The electronic circuit is protected by a humidity proof coating, but frequent exposures to humidity may affect the protection provided. It is also important to keep the covers tightened in place. Every time they are removed, the threads are exposed to corrosion, since these parts cannot be protected by painting. Code approved sealing methods on conduit entering the transmitter should be employed.

Although the transmitter is virtually insensitive to vibration, installation close pumps, turbines or other vibrating equipment should be avoided.

## Mounting

The **TP290** mounting depends on the type movement, linear or rotary. Two brackets are required for mounting, one for the magnet and the other for the transmitter itself.

#### NOTE

Make sure that arrow engraved on the magnet coincides with the arrow engraved on the Position Transmitter when the system is in mid travel. When mounting the the Position Transmitter, consider that:

- 1. There is no friction between the internal magnet face and the position sensor salience all over the travel (rotary or linear).
- 2. A minimum distance of 2 mm to of 4 mm distance is recommended between the magnet external face and the Position Transmitter face.

Should the transmitter installation change, or magnet change, or should any other modification, the transmitter will require a re-calibration.

#### IMPORTANT

If the self diagnostics detect a transmitter failure, for example the loss of the power, the analog signal will go to 3.9 mA or to 21.0 mA to alert the user (High or low alarm signal is user selectable).

The following Figures 1.1 and 1.3 show both linear and rotary typical mounting:

#### **Rotary Movement**

Install the magnet on the valve stem using the magnet mounting bracket.

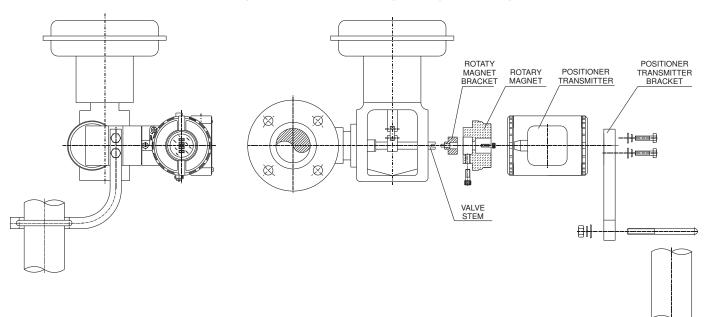


Figure 1.1 - Transmitter on a Rotary Actuator

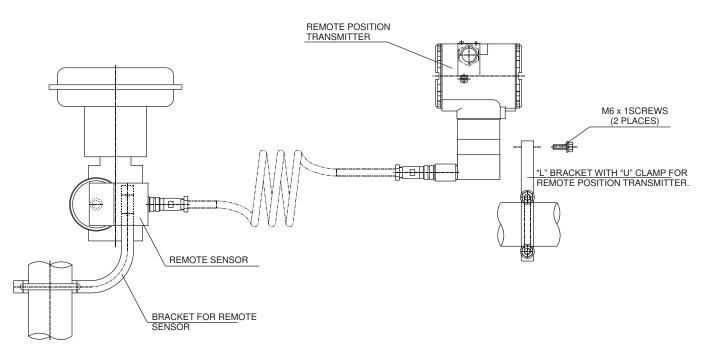


Figure 1.2 – Position Transmitter on Rotary Actuator with Remote Position Sensor

#### **Linear Movement**

Install the magnet on the valve stem using the magnet mounting bracket.

The linear magnet movement must be orthogonal in relation to the main axis of the position transmitter. For example, if the linear magnet movement is vertical, the transmitter main axis must be horizontal, as show in Figure 1.3.

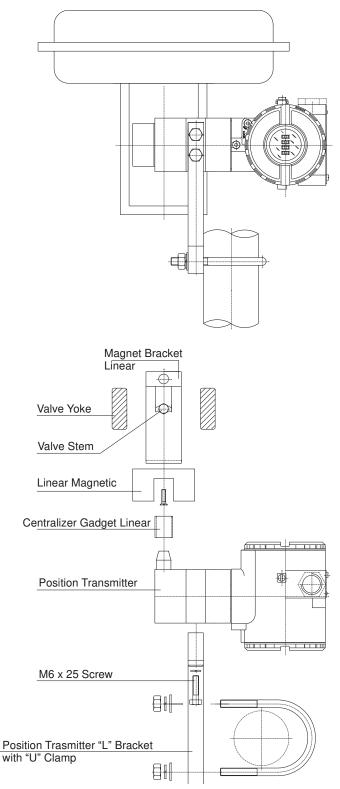


Figure 1.3 - Transmitter on a Linear Actuator

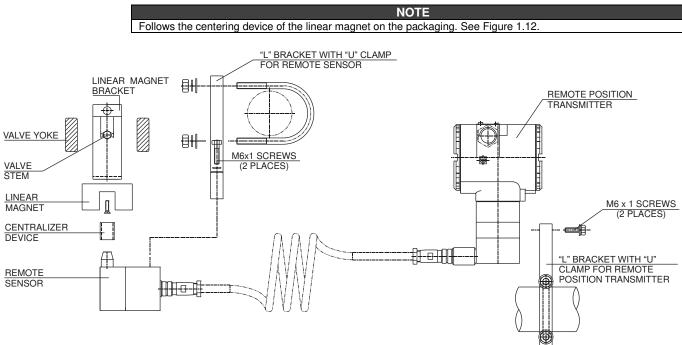
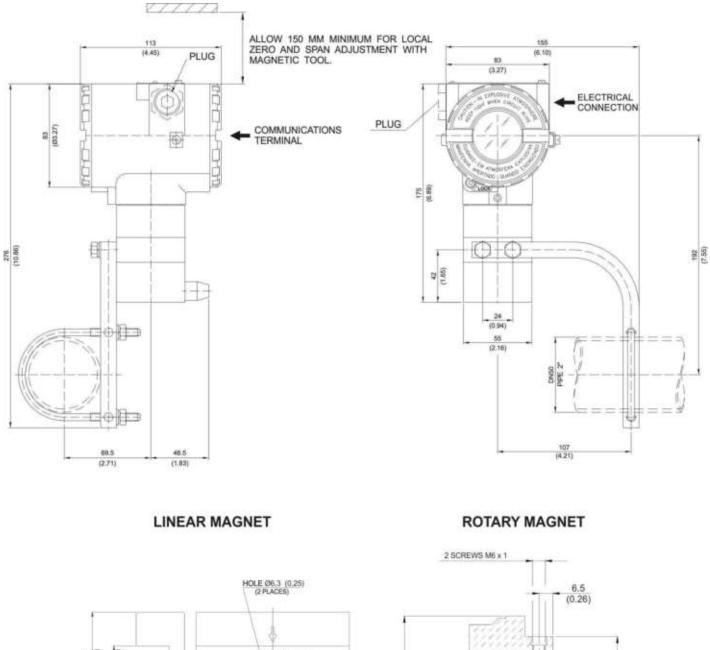


Figure 1.4 – Position Transmitter on Linear Actuator with Remote Position Sensor

See below the **TP290**, dimensional drawings.



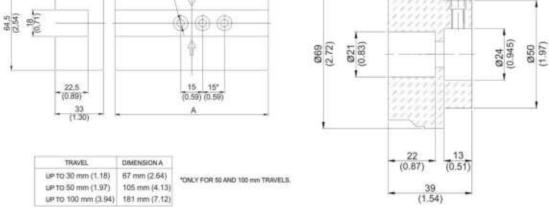


Figure 1.5 – TP290 Dimensional Drawing / Magnets Dimensional Drawing

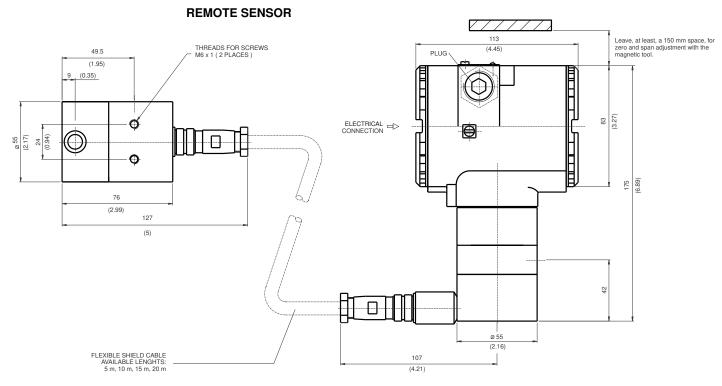


Figure 1.5.a – Remote Sensor Dimensional Drawing

#### SPECIAL MOUNTING BRACKET - ROTARY VDI / VDE NAMUR

Mounting bracket of the position transmitter for rotary valves actuated via type actuators rack and pinion, designed to comply with NAMUR VDI/VDE.

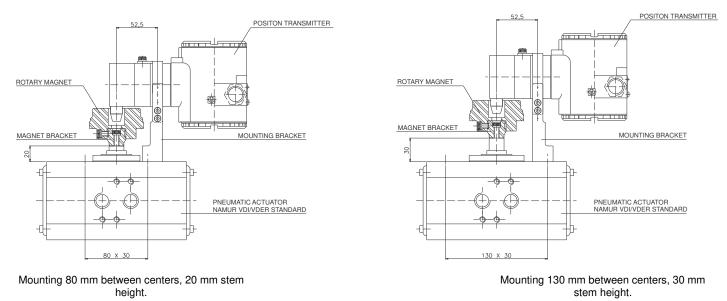


Figure 1.5.b – Special Mounting Bracket Dimensional Drawing - Rotary VDI / VDE NAMUR

### **Electronic Housing Rotating**

The electronic housing rotates for a better digital display reading. To rotate it, release the housing rotation screw.

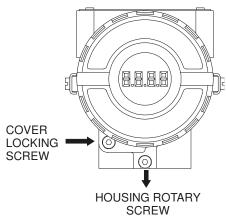


Figure 1.6 - Cover Locking and Housing Rotation Set Screw

The digital display also rotates for better reading. See Section 4. To access the terminal block for electronic connections, remove the cover locking screw.

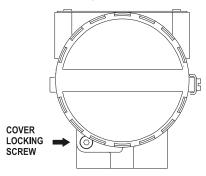


Figure 1.7 - Cover Locking Screw

## **Electric Wiring**

The terminal block accepts forks or eye-type connectors. **Test terminals** allow measuring the current in the 4 - 20 mA loop, without opening it. To measure it, connect a multimeter in the mA scale in the "–" and "+" terminals.

For convenience there are two ground terminals: one inside the cover and one external, located close to the conduit entries.

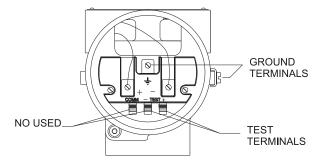


Figure 1.8 - Wiring Block

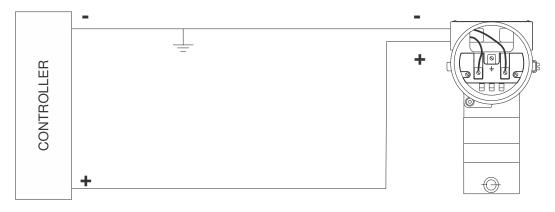
Use of twisted pair (22 AWG or greater than) cables is recommended. Avoid routing signal wiring cables close to power cables or switching equipment.

The **TP290** is protected against reverse polarity, and supports LI50 mA without damage.

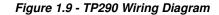
The following figures show the possibilities for TP290 connections.

The **TP290** connection could be done conform the figure 1.9 and 1.10.

It is also recommended to ground the shield of shielded cables at one end only. The non grounded end must be carefully isolated.



SIGNAL LOOP MAY BE GROUNDED AT ANY POINT OR LEFT UNGROUNDED.



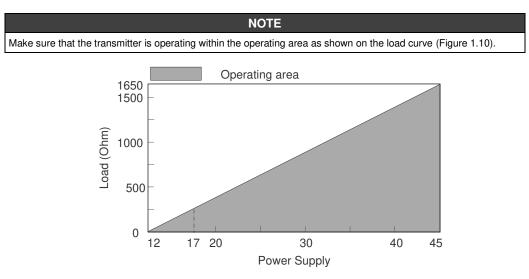


Figure 1.10 - Load Curve

# Recommendations for mounting Approved Equipment with the IP66/68 W certifications ("W" indicates certification for use in saline atmospheres)

NOTE This TP290 certification is valid for stainless steel transmitter manufactured, approved with the certification IP66/68 W. All transmitter external material, such as plugs, connections etc., should be made in stainless steel. The electrical connection with 1/2" – 14NPT thread must use a sealant. A non-hardening silicone sealant is recommended. The instrument modification or replacement parts supplied by other than authorized representative of Smar is prohibited and will void the certification.

## Rotary and Linear Magnet

The Figure 1.11 shows typical shapes for both magnets. For better transmitter performance, the linear magnet is presented with different lenghts. Consult the ordering code table for the best choice.



Figure 1.11 – Linear and Rotary Magnet Models

Centering Device of the Linear Magnet

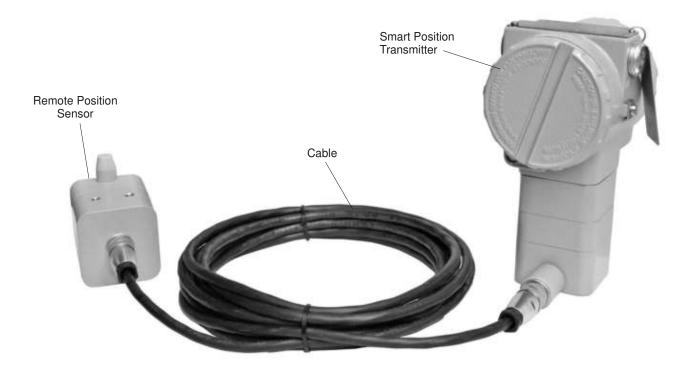


NOTE Centralizing device of the linear magnet is used for any model of linear mounting bracket.

Figura 1.12 - Centralizing device of the linear magnet

### **Remote Position Sensor**

The remote magnetic position sensor, based on hall effect, is recommended for high temperature or extreme vibration applications. It prevents excessive wear of the equipment and, consequently, increasing the transmitter lifetime



#### Figure 1.13 - Remote Position Sensor

The electric signals on the remote sensor's cable and connections are of low intensity. Therefore, when installing the cable inside the conduit (maximum limit 20 (meters) length), keep it away from possible sources of induction and/or magnetic interference. The cable supplied by Smar is shielded with excellent protection against electromagnetic interference, but despite of this protection, it is recommended to avoid the cable sharing the same conduit with other cables.

The connector for Remote Position Sensor is easy to handle and simple to install.

See the installation procedure:



Figure 1.14 - Connecting the Cable to the Remote Position Sensor



Figure 1.15 - Connecting the Cable to the Position Transmitter

## Installation in Hazardous Areas

Consult the Appendix A for Hazardous Location Approvals.

# **OPERATION**

## Functional Description – Hall Sensor

The Position Sensor supplies an output voltage proportional to the applied magnetic field. This magnetic sensor, based on hall effect, is ideal for sensing linear or rotative position. The mechanical vibrations do not affect Position Sensor.

## Functional Description-Electronics

Refer to the block diagram (Figure 2.1). The function of each block is described below.

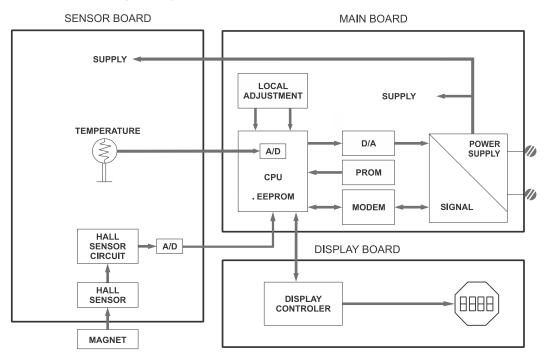


Figure 2.1 – TP290 Block Diagram

#### A/D

Receives the 4 - 20 mA signal and converts it in the digital format for the CPU.

#### D/A

Receives the signal from the CPU and converts it to an analog voltage proportional the measurement position.

#### Hall Effect Sensor

Measures the actual position.

#### **Temperature Sensor**

Measures the temperature of the control circuit and inform the CPU.

#### CPU Central Processing Unit, RAM, PROM and EEPROM

The CPU is the intelligent portion of the transmitter, being responsible for the management and operation of block execution, self-diagnostics and communication. The program is stored in PROM. For temporary storage of data there is a RAM. The data in the RAM is lost if the power is switched off, however the device also has a nonvolatile EEPROM where data that must be retained is stored. Examples of such data are: calibration and **TP290** configuration.

#### **Power Supply**

The transmitter circuit receives supply from a 4 - 20 mA power supply or take power of Loop\_Line to power the transmitter circuit this is, of course, limited to 3.8 mA.

#### **Display Controller**

Receives data from the CPU and drives the (LCD) Liquid Crystal Display.

#### Local Adjustment

Local adjustment is provided by means of two magnetically actuated switches with no external electric or mechanical contact, by using a magnetic screwdriver.

#### THE LOCAL INDICATOR

The local indicator is required for signaling and operation in local adjustment.

#### **Normal Indicator**

Monitoring

During normal operation, the **TP290** remains in the monitoring mode and the display indicates the valve position, either as a percentage or as a current readout. The magnetic tool activates the local programming mode, by inserting it in orifice Z on the housing.

The possible configuration and monitoring operation are shown on Figure 2.2.

Upon receiving power, the **TP290** initializes the position indication on the display, by showing model **TP290** and its software version (X.XX). Should the indication be higher than 119999 it will be displayed as a two digit and an exponent.

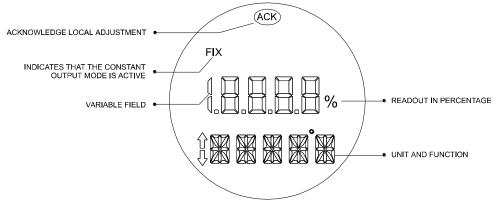


Figure 2.2 – Normal Indicator

During normal operation, TP290 remains in the monitoring mode. Figure 2.3 shows the positioning.

The display simultaneously shows a readout and some other information.

Normal displaying is interrupted when the magnetic tool is placed in office Z (Local Adjustment), entering the programming mode local adjustment.

The above mentioned figure shows the result of tool insertion in orifices Z and S, which inform, respectively, movement and actuation of the selected options.

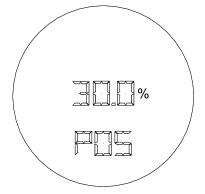


Figure 2.3 – Typical Indicator

# PROGRAMMING USING LOCAL ADJUSTMENT

To enable local adjustment, the jumper "W1" located on top of the main board shall be connected to the pins where the word "ON" is engraved on the circuit board.

There are two orifices on the Transmitter, under the nameplate, identified by "**S**" and "**Z**" respectively, which provide access to two magnetic switches actuated by means of a magnetic tool (Refer to Figure 3.1).

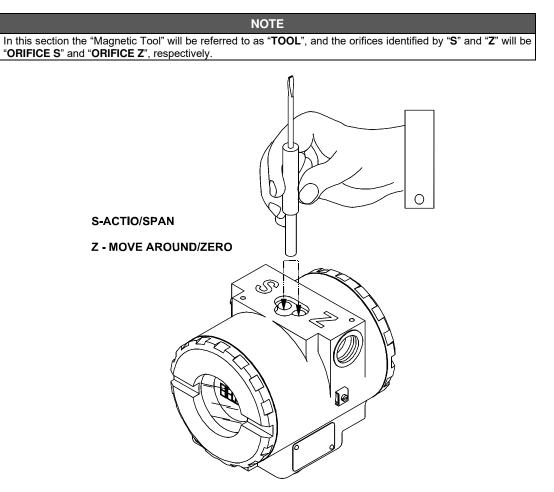


Figure 3.1 – Orifices of the Local Adjust

Table 3.1- shows the results of what actions on "Z" and "S" cause on the TP290.

ORIFICE	ACTION
Z	Function browsing.
S	Selects the displayed function.

Table 3.1 - Orifices on the Case

### Jumper Connection

#### Jumper W2 connected in SI

If the jumper W2 is connected in SI, simple local adjustment enabled, the calibration can be done at the position of 0% inserting the cable of the key in the hole Z and 100% inserting it in the hole S.

#### Jumper W2 Connected in COM

With the jumper connected in COM, complete local adjustment enabled, it is allowed to alter the unit to be shown, the Direct or Reverse indication and to calibrate the lower position (LOPOS) or the upper position (UPPOS).

NOTE
After gauging these values, we advised to leave the jumper W2 in OFF (disabled) to avoid that somebody for negligence adjusts the transmitter erroneously.

## Local Programming Tree

The programming tree is a tree shaped structure with a menu of all available software functions, as shown on Figure 3.2.

While in local Adjustment, it is possible to browse through all configuration options by keeping the magnetic tool in orifice "Z". Upon choosing the option as described, place the tool in orifice "S" in order to actuate.

By keeping the tool in orifice "**S**" it is possible to continuously actuate the selected parameter, since this is a numeric valve. Actions by increment are performed by repeatedly placing and removing the magnetic tool until reaching the desired valve.

NOTE Every parameter actuation shall be performed judiciously, since actuation writes configuration parameters on a permanent basis and does not require confirmation by the use. Once an actuation is performed it is assumed to be the desired configuration.

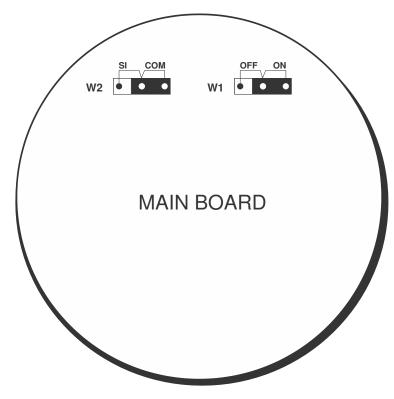


Figure 3.2 – Jumpers W2 and W1

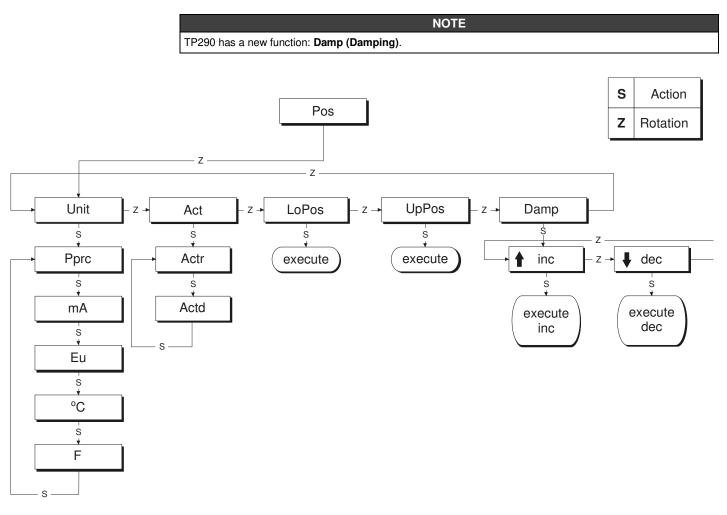
## Procedure to Calibrate the Position Transmitter

#### Calibration Using the Jumper in Simple Local Adjustment

If the Simple Local adjustment is enabled, only the Lower and Upper Position can be adjusted. To adjust them position the magnet in the lower point of the stroke and insert the magnet part of the tool in the hole Z. To adjust the upper value, position the magnet in the upper point and insert the tool in the hole S. After this, move the magnet and check the indications of other positions. Repeat the procedures if necessary.

#### Calibration using the jumper in Complete Local Adjustment

If the Complete Local adjustment is enabled, the unit and the direct or reverse indication can be configured and the lower and upper positions of the stroke can be adjusted. To adjust the lower and upper position, refer to the procedures of the calibration of the Simple Local Adjustment. The Figure 3.3 shows how to travel the options.





**NOTE** Remove the Magnetic Tool of the orifice to Save (to execute) the selected option. When the display shows the symbol **ACK**: option was accepted

## DESCRIPTION OF THE PARAMETERS OF THE LOCAL ADJUSTMENT CONFIGURATION TREE

#### POS - Position in Percentage

#### Unit - Engineering Unit or Percentage

Pprc - Position in Percentage.
mA (Mile Ampere) - Current.
Eu (End User's choice) - Position.
<sup>o</sup>C (Degrees Celsius) - Temperature.
F (Degrees Fahrenheit) - Temperature.

#### Act - Action

Actr - Reverse action.

Actd - Direct action.

#### LoPos (0% Position) - TRIM of inferior position.

#### UpPos (100% Position) - TRIM of Superior Position.

Damp (Damping) - reduction function.

**Inc -** Increment. **Dec -** Decrement.

# **MAINTENANCE PROCEDURES**

### General

SMAR **TP290** to read Position are extensively tested and inspected before delivery to the end user. Nevertheless, during their design and development, consideration was given to the possibility of repairs by the end user, if necessary.

In general, it is recommended that the end user do not try to repair printed circuit boards. Instead, he should have spare circuit boards, which may be ordered from **SMAR** whenever necessary.

# Recommendations for mounting Approved Equipment with the IP66/68 W certifications ("W" indicates certification for use in saline atmospheres)

#### NOTE

The certification is valid for stainless steel transmitter manufactured, approved with the certification IP66/68 W. All transmitter external material, such as plugs, connections etc., should be made in stainless steel.

The electrical connection with 1/2" – 14NPT thread must use a sealant. A non-hardening silicone sealant is recommended.

The instrument modification or replacement parts supplied by other than authorized representative of Smar is prohibited and will void the certification.

## **Diagnostics**

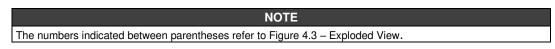
In order to carry out the diagnostics, refer to table 4.1.

DIAGNOSTICS							
SYMPTOM	PROBABLE ERROR SOURCE:						
POSITION IS NOT DISPLAY	<ul> <li>Position Transmitter Connections.</li> <li>Check wiring polarity and continuity.</li> <li>Power Supply</li> <li>Check load curve.</li> <li>Check power supply output.</li> <li>Voltage should be between 12 Vdc and 45 Vdc at the transmitter terminals.</li> <li>Electronic Circuit Failure</li> <li>Check the boards for malfunctions and faulty boards for spare ones.</li> </ul>						
NO RESPONSE FOR THE INPUT SIGNAL	<ul><li>Calibration</li><li>Check the Position Transmitter calibration points.</li></ul>						

#### Table 4.1 - TP290 Diagnostics Without the Programmer

## **Disassembly Procedure**

Refer to **TP290** Exploded View figure 4.3. Make sure to disconnect power supply before disassembling the position transmitter.



#### Transducer

To remove the transducer from the electronic housing, disconnect before the electrical connections (in the field terminal side) and the main board.

Loosen the hex screw (6) and carefully unscrew the electronic housing from the transducer, observing that the flat cable is not excessively twisted.

#### **Electronic Circuit**

To remove the circuit board (5) and indicator (4), first loose the cover locking (7) on the side not marked "Field Terminals", then unscrew the cover (1).

#### WARNING

The boards have CMOS components which may be damaged by electrostatic discharges. Observe correct procedures for handling CMOS components. It is also recommended to store the circuit boards in electrostatic-proof cases.

#### CAUTION

Do not rotate the electronic housing more than 270° without disconnecting the electronic circuit from the power supply.



Figure 4.1 – Transducer Rotation Stopper

Loosen the two screws (3) that anchors the indicator and the main circuit board. Gently pull out the indicator, and then the main board (5).

### **Reassembly Procedure**

#### WARNING Do not assemble the main board with power on.

#### Transducer

Mount the transducer to the housing turning clockwise until it stops. Then turn it counterclockwise until it faces the square of electronic housing to the square of transducer. Tighten the hex screw (6) to lock the housing to the transducer.

#### Electronic Circuit

Plug transducer connector and power supply connector to main board (5). Attach the display to the main board. Observe the four possible mounting positions. The  $\uparrow$  mark indicates up position.

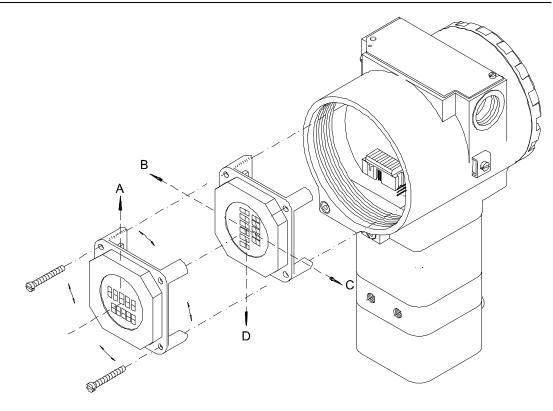


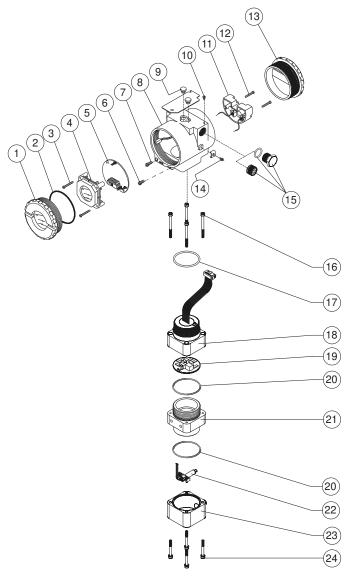
Figure 4.2 – Four Possible Positions of the Indicator

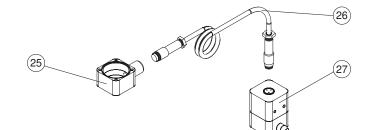
Anchor the main board (5) in the housing (8) with their screws (3). After tightening the protective cover (1), mounting procedure is complete. The transmitter is ready to be energized and tested.

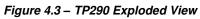
## Interchangeability

Main board can be replaced by a similar new one keeping the operational features unchanged. The transducer EEPROM has all the information related to the TRIM and factory default configuration.

## Exploded View







## Accessories

ACCESSORIES								
ORDERING CODE DESCRIPTION								
SD-1	Magnetic Tool for Local Adjustment.							
400-1176	400-1176 Teflon guide for linear magnet.							
400-1177     Teflon guide for rotary magnet.								

## Spare Parts List

SPARE PARTS LIST								
DESCRIPTION OF PARTS		POSITION	CODE	CATEGORY (NOTE 1)				
COVER WITH WINDOW	. Aluminum . 316 SS	1	204-0103					
COVER O-RING (NOTE 3)	. Buna-N	1 2	204-0106 204-0122	В				
	. Units with indicator	3	304-0118					
ALUMINUM HOUSING MAIN BOARD SCREW	. Units without indicator	3	304-0117					
STAINLESS STEEL HOUSING MAIN BOARD SCREW	. Units with indicator	3	204-0118					
	. Units without indicator	3	204-0117					
DIGITAL INDICATOR		4	214-0108					
MAIN ELECTRONIC CIRCUIT BOARD		5	400-0100	A				
HOUSING LOCKING SCREW	. M4 Screw	6	204-0121					
	. M6 Without Head Screw	6	400-1121					
		7	204-0120					
HOUSING (NOTE 2)		8	(NOTE 5)					
		9	204-0114					
		10	204-0116					
TERMINAL BLOCK ISOLATOR		11	400-0058					
TERMINAL BLOCK HOLDING BOLT	. Cover Aluminum	12	304-0119					
	. Cover 316 SS	12	204-0119 204-0102					
COVER WITHOUT WINDOW	. Aluminum . 316 SS	13 13	204-0102 204-0105					
EXTERNAL GROUND BOLT		14	204-0124					
SIX-SIDED INTERNAL PLUG	. 1/2" NPT Bichromatized Carbon SteeL BR-EX D	15	400-0808					
	. 1/2" NPT 304 SST BR-EX D	15	400-0809					
SIX-SIDED INTERNAL PLUG	. 1/2" NPT Bichromatized Carbon SteeL	15	400-0583-11					
	. 1/2" NPT 304 SST	15	400-0583-12					
SIX-SIDED EXTERNAL PLUG	. M20 X 1.5 316 SST . PG13.5 316 SST	15	400-0810 400-0811					
RETAINING BUSHING	. 3/4" NPT 316 SST	15 15	400-0811					
CONNECTION COVER SCREW	. 3/4 NFT 310 331	15	400-0812					
	. Aluminum	16, 17, 18,	400-0884					
CONNECTION COVER SET	. 316 SS	19 16, 17, 18,	400-0885					
		19						
O-RING, Neck (NOTE 3)	. Buna-N	17	204-0113	В				
CONNECTION COVER	. Aluminum	18	400-0074					
ANALOG BOARD	. 316 SS	18 19	400-0391 400-0637					
UNION BLOCK O-RING		20	400-0037	В				
	. Aluminum	20	400-0005	Б				
UNION BLOCK	. 316 SS	21	400-0387					
POSITION SENSOR COVER SET	. Aluminum	22, 23, 24	400-0656					
	. 316 SS	22, 23, 24	400-0657					
POSITION SENSOR BRACKET + POSITION SENSOR SENSOR + FLAT CABLE		22	400-0090					
POSITION SENSOR COVER	. Aluminum	23	400-0089					
	. 316 SS	23	400-0396					
POSITION SENSOR COVER BOLT		24	400-0092					
REMOTE POSITION SENSOR COVER SET(NOTE 4)	. Aluminum	25	400-0853					
	. 316 SS	25	400-0854					

#### TP290 – Operation, Maintenance and Instructions Manual

SPARE PARTS LIST							
DESCRIPTION OF PARTS	POSITION	CODE	CATEGORY (NOTE 1)				
	. 5 M	26	400-0857				
	. 10 M	26	400-0858				
CABLE SET + CONNECTOR	. 15 M	26	400-0859				
	. 20 M	26	400-0860				
	. Aluminum	27	400-0855				
REMOTE EXTENSION SET	. 316 SS	27	400-0856				
	. Aluminum	16 a 24	400-0038				
TRANSDUCER SET	. 316 SS	16 a 24	400-0400				
	. Carbon Steel	-	400-0339				
MOUNTING BRACKET,"L" + CLAMP "U" TO PIPE 2"	. 316 SS	-	400-0340				
	. Linear up to 50 mm	-	400-0035				
MACHETC	. Linear up to 100 mm	-	400-0036				
MAGNETS	. Linear up to 30 mm		400-0748				
	. Rotary	-	400-0037				

ΝΟΤΑ

Note 1: For category A it is recommended to keep in stock 25 parts installed for each set and 50 for category B.

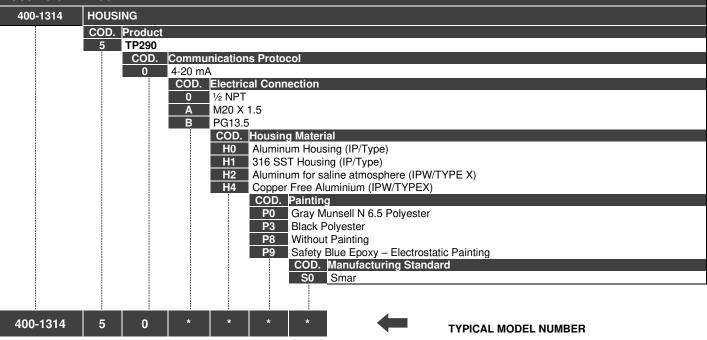
Nota 2: Includes terminal block isolator, bolts (cover locking, ground and terminal block isolator) and identification plate without certification.

Note 3: O-rings are packaged with 12 units.

Nota 4: Includes cover, position sensor flat cable, and extension cable connector.

Nota 5: To specify the housing, use HOUSING ORDER CODE table.

#### HOUSING ORDER CODE



\* Select item.

# **TECHNICAL CHARACTERISTICS**

## Function Specifications

Travel	Linear Motion: 3 to 100 mm.								
Traver	Rotary Motion: 30° to 120° roation angle.								
Output Signal	Two-wire, 4 to 20 mA.								
	I WU-WIIE, 4 LU ZU IIIA.								
Reverse Polarity Protection	12 to 45 Vdc.								
Load Limitation	Operating area 1650 1500 0 1000 0 1000 0 1000 0 1000 0 1000 0 1000 10								
Indicator	Optional 4 <sup>1</sup> / <sub>2</sub> - digit numerical and 5-character alphanumerical LCD indicator.								
Hazardous Area	Explosion-proof and intrinsically safe (ATEX (NEMKO and DEKRA EXAM), FM, CEPEL and CSA).								
Certifications	Designed to comply with European regulations ATEX 94/9/EC and LVD 2006/95/EC standards.								
Zero and Span Adjustments	Non-interactive, via local adjustment or digital communication.								
Temperature Limits	Ambient:       - 40       to       85 °C       (- 40       to       185 °F)         Storage:       - 40       to       90 °C       (- 40       to       194 °F)         Digital Display:       - 10       to       75 °C       (14       to       167 °F)       operation;         - 40       to       85 °C       (- 40       to       185 °F)       without damage.         Remote Sensor:       - 40       to       105°C       (- 40       to       221°F)								
Failure Alarm	In case of sensor or circuit failure, the self-diagnostics drivers the output to 3.9 or 21.0 mA, according to the user's choice.								
Turn-on Time	Performs within specifications in less than 5.0 seconds after power is applied to the transmitter.								
Update Time	Approximately 150 ms.								
Humidity Limits	0 to 100% RH.								
Output Action	Direct or Reverse.								
Actual Position Sensing	Magnetic (Non-contact) via Hall Effect.								
Configuration	Can be done through local adjust.								

## Performance Specifications

Reference conditions: range starting at zero, temperature 25°C (77°F), power supply of 24 Vdc.

Accuracy	Linearity, hysteresis and repeatability effects are included.						
<b>Resolution</b> $\leq 0.1\%$ F.S.							
<b>Repeatability</b> $\leq 0.5\%$ F.S.							
Hysteresis	≤ 0.2% F.S.						
Stability	± 0.1% of F.S. for 12 months.						
Temperature Effect	± 0.8%/20ºC of F.S.						
Power Supply Effect	$\pm$ 0.005% of calibrated F.S. per volt.						
Electromagnetic Interface Effect	Designed to comply with European Directive EMC 2004/108/EC.						

## **Physical Specifications**

<b>Electrical Connection</b>	1/2 - 14 NPT, PG 13.5, or M20 x 1.5 metric.						
Material of	Injected low copper aluminum with polyester painting or 316 Stainless Steel housing, with BUNA-N O-						
Construction rings on cover.							
Mounting Bracket Plated carbon steel with polyester painting or 316 SST.							
Identification Plate	316 SST.						
Approximate Weights	<ul> <li>TP <ul> <li>1.5 kg in Aluminum (without mounting bracket);</li> <li>3.3 kg in Stainless Steel (without mounting bracket).</li> </ul> </li> <li>Remote sensor: <ul> <li>0.58 kg in Aluminum.</li> <li>1.5 kg in Stainless Steel.</li> </ul> </li> <li>Cable and remote sensor connectors:</li> </ul>						
	Cable 0.045 kg/m; 0.05 kg for each connector.						

## Ordering Code

MODEL	POSITION TR	RANSMI	TTER											
TP290	4 to 20 mA													
1	COD. Local													
		1 With Local Display COD. Mounting Bracket												
1		DD. Mounting Bracket												
1	1	Carbon S		" ı clamn	"I I" nine	2" (3)								
	2	Stainless												
1	3	Carbon S				. ,								
I I	4	Stainless		-										
1	7	Carbon S	Steel, "L'	" + clamp	"U" pipe	2" - (316 \$	SST) acces	ssories.	(3)					
I		COD.	Electri	cal Conne	ection									
			1/2" - 1								3			SST) - with adapter
						. ,	- with ada	•			Α	M20 X 1.		
1						· /	- with ada	lpter		-	В	PG 13.5	DIN	
			<u>COD.</u> 1	Type c Rotary	of Actua	ator								
1			5	-	Stroke un	to 50 mm								
i			7			to 100 mr								
i						to 30 mm								
1			1			FIONS (1)	)							
1			i	COD.										
1				HO		um (IP/TY	,						for saline atmosphe	, ,
1				H1			eel (IP/TYP cation Pl	,			H4	Copper Fi	ree Aluminium (IPW/	TYPEX)
I				i		FM: XP,		ale				16	Without certification	n
1		i	ł	i			DMT): Ex-ia	a, IP					NEMKO - Ex-d	
ļ		i		i	15		Ex-d, Ex-ia							
i			-		:	COD.	Painting	]						
i			i.				Gray Mun		5 Polyes	ster				
i		1				-	Black Poly							
1		-	i			-	Without Pa Blue Safe	•	Elect	traatatia	Dain	ting		
1			i	-			COD. T			liostatic	raii	ung		
1				i i				Vith TAG						
1				i				Blank						
1			-	i			<b>J2</b> A	According	g to use	r's notes	S			
1		i				1		COD.			nting	g (2)		
			-	:		1			Full Mou	0	_			
İ			i.			1				sensor		n cable m cable		
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TP290 -	1 0	- 0	1	*	• *	*	*	*	*			TY	PICAL MODEL N	UMBER
										•				

NOTE

Leave it blank when there are not optional items.
 Consult us for classified areas applications.
 Magnet mounting bracket not supplied with the TP.

# **CERTIFICATIONS INFORMATION**

## European Directive Information

Consult www.Smar.com for the EC declarations of conformity and certificates.

#### Authorized representative/importer located within the Community:

Smar Europe BV De Oude Wereld 116 2408 TM Alphen aan den Rijn Netherlands

#### ATEX Directive 2014/34//EU - "Equipment for explosive atmospheres"

The EC-Type Examination Certificate is released by DNV GL Presafe AS (CE2460) and DEKRA Testing and Certification GmbH (CE0158).

Designated certification body that monitors manufacturing and released QAN (Quality Assurance Notification) and QAR (Quality Assessment Report) is Nemko AS (CE0470).

#### LVD Directive 2014/35/EU - "Low Voltage"

According the LVD directive Annex II, electrical equipment for use in an explosive atmosphere is outside the scope of this directive.

According to IEC standard: IEC 61010-1 Safety requirements for electrical equipment for measurement, control, and laboratory use - Part 1: General requirements.

## ROHS Directive 2011/65/EU - "Restriction of the use of certain hazardous substances in electrical and electronic equipment"

For the evaluation of the products the following standards were consulted: EN 50581.

#### EMC Directive 2014/30/EU - "Electromagnetic Compatibility"

For products evaluation, the standard IEC 61326-1 were consulted and to comply with the EMC directive the installation must follow these special conditions:

Use shielded, twisted-pair cable for powering the instrument and signal wiring. Keep the shield insulated at the instrument side, connecting the other one to the ground.

## Hazardous locations general information

#### Ex Standards:

IEC 60079-0 General Requirements IEC 60079-1 Flameproof Enclosures "d" IEC 60079-7 Increased Safe "e" IEC 60079-7 Increased Safet "i" IEC 60079-18 Encapsulation "m" IEC 60079-26 Equipment with equipment protection level (EPL) Ga IEC 60079-31 Equipment dust ignition protection by enclosure "t" IEC 60529 Classification of degrees of protection provided by enclosures (IP Code) IEC 60079-10 Classification of Hazardous Areas IEC 60079-14 Electrical installation design, selection and erection IEC 60079-17 Electrical Installations, Inspections and Maintenance IEC 60079-34 Application of quality systems for equipment manufacture

#### Warning:

Explosions could result in death or serious injury, besides financial damage.

Installation of this instrument in hazardous areas must be in accordance with the local standards and type of protection. Before proceedings with installation make sure that the certificate parameters are in accordance with the classified hazardous area.

#### Maintenance and Repair

The instrument modification or replaced parts supplied by any other supplier than authorized representative of Smar is prohibited and will void the Certification.

#### Marking Label

The instrument is marked with type of protection options. The certification is valid only when the type of protection is indicated by the user. Once a particular type of protection is installed, do not reinstall it using any other type of protection.

#### Instrinsic Safety / Non Incendive application

In hazardous areas with intrinsic safety or or non-incendive requirements, the circuit entity parameters and applicable installation procedures must be observed.

The instrument must be connected to a proper intrinsic safefy barrier. Check the intrinsically safe parameters involving the barrier and equipment including the cable and connections. Associated apparatus ground bus shall be insulated from panels and mounting enclosures. Shield is optional, when using shielded cable, be sure to insulate the end not grounded.

Cable capacitance and inductance plus Ci and Li must be smaller than Co and Lo of the Associated Apparatus. It is recommended do not remove the housing covers when powered on.

#### Explosionproof / Flameproof application

Only use Explosionproof/Flameproof certified Plugs, Adapters and Cable glands.

The electrical connections entries must be connected using a conduit with sealed unit or closed using metal cable gland or metal blanking plug with at least IP66.

Do not remove the housing covers when powered on.

#### Enclosure

The electronic housing and sensor threads installed in hazardous areas must have a minimum of 6 fully engaged threads.

The covers must be tightening with at least 8 turns, to avoid the penetration of humidity or corrosive gases, and until it touches the housing. Then, tighten more 1/3 turn (120°) to guarantee the sealing. Lock the housing and covers using the locking screw.

#### Degree of Protection of enclosure (IP)

IPx8: Second numeral meaning continuous immersion in water under special condition defined as 10m for a period of 24 hours (Ref: IEC60529).

IPW/ TypeX: Supplementary letter W or X meaning special condition defined as saline environment tested in saturated solution of NaCl 5% w/w at 35°C for a period of 200 hours (Ref: NEMA 250/ IEC60529).

For enclosure with IP/IPW/TypeX applications, all NPT threads must apply a proper water-proof sealant (a non-hardening silicone group sealant is recommended).

### Hazardous Locations Approvals

#### FM Approvals

FM 3010145 / FM 3007267 IS Class I, II, III Division 1, Groups A, B, C and D, E, F, G XP Class I, Division 1, Groups A, B, C, D DIP Class II, III Division 1, Groups E, F, G NI Class I, Division 2, Groups A, B, C, D

Option: Type 4X or Type 4 Entity Parameters: Vmax = 30 Vdc, Imax = 110 Ma, Ci = 5 nF, Li = 12 uH Temperature Class: T4 Ambient Temperature: 60°C (-20 to 60 °C)

Drawing 102A-0604, 102A-1235, 102A-1348, 102A-1954, 102A-1955

#### ATEX DNV GL Presafe AS

Explosion Proof (PRESAFE 21 ATEX 17657X) II 2G Ex db IIC T6 Gb Ta -20 °C to +60 °C Options: IP66/68W or IP66/68

Special Conditions for Safe Use ATEX and IECEx certified cable gland to be used. Repairs of the flameproof joints must be made in compliance with the structural specifications provided by the manufacturer. Repairs must not be made on the basis of values specified in tables 3 of EN/IEC 60079-1.

The Essential Health and Safety Requirements are assured by compliance with: EN 60079-0:2018 General Requirements EN 60079-1:2014 Flameproof Enclosures "d"

Drawing 102A-1449, 102A-1505

#### **IECEx DNV GL Presafe A/S**

Explosion Proof (IECEx PRE 21.0015X) Ex db IIC T6 Gb Ta -20 °C to +60 °C Options: IP66/68W or IP66/68

Special Conditions for Safe Use ATEX and IECEx certified cable gland to be used. Repairs of the flameproof joints must be made in compliance with the structural specifications provided by the manufacturer. Repairs must not be made on the basis of values specified in tables 3 of EN/IEC 60079-1.

The Essential Health and Safety Requirements are assured by compliance with: IEC 60079-0:2017 General Requirements IEC 60079-1:2014-06 Equipment protection by flameproof enclosures "d"

Drawing 102A2163, 102A2164

#### **DEKRA Testing and Certification GmbH**

Intrinsic Safety (DMT 00 ATEX E 085) Group I, Category M2, Ex ia, Group I, EPL Mb Group II, Category 2 G, Ex ia, Group IIC, Temperature Class T4/T5/T6, EPL Gb Supply and signal circuit intended for connection to an intrinsically safe 4-20 mA current loop: Ui = 28 Vdc, Ii = 93 mA, Ci  $\leq$  5 nF Li = Neg

Maximum Permissible power:

1					
	Max. Ambient temperature Ta	Temperature Class	Power Pi		
	85°C	T4	700 mW		
	75°C	T4	760 mW		
	44°C	Т5	760 mW		
	50°C	T5	700 mW		
	55°C	T5	650 mW		
	60°C	T5	575 mW		
	65°C	Т5	500 mW		
	70°C	Т5	425 mW		
	40°C	Т6	575 mW		

Ambient Temperature: -40°C ≤ Ta ≤ + 85°C

The Essential Health and Safety Requirements are assured by compliance with: EN 60079-0:2012 + A11:2013 General Requirements EN 60079-11:2012 Intrinsic Safety "i"

Drawing 102A-1449, 102A-1505, 102A-1578, 102A-1579

#### CEPEL (Centro de Pesquisa de Energia Elétrica)

Segurança Intrínseca (CEPEL 07.1501X)

CEPEL 07.1501X Ex ja IIC T5 Ga					
IP66W/IP68W (aço inox e alumínio Copper Free)	IP66/IP68 (alumínio)				
Ui = 30 V li = 100 mA Pi = 0,7 W Ci = 6,4 nF Li = desp					
T <sub>amb</sub> : -20 °C a +50 °C para T5					

Prova de Explosão (CEPEL 01.0016)



#### Observações:

A validade deste Certificado de Conformidade está atrelada à realização das avaliações de manutenção e tratamento de possíveis não conformidades, de acordo com as orientações do Cepel, previstas no Regulamento de Avaliação da Conformidade. Para verificação da condição atualizada de regularidade deste Certificado de Conformidade deve ser consultado o banco de dados de produtos e serviços certificados do Inmetro.

O número do certificado é finalizado pela letra "X" para indicar que para a versão do Transmissor de Posição, Intrinsecamente Seguro, modelos TP290, TP301, TP302 e TP303 equipado com invólucro fabricado em liga de alumínio, somente pode ser instalado em "Zona 0", se durante a instalação for excluído o risco de ocorrer impacto ou fricção entre o invólucro e peças de ferro/aço.

A tampa do invólucro possui uma plaqueta de advertência com a seguinte inscrição: "ATENÇÃO - NÃO ABRA ENQUANTO ENERGIZADO", ou similar tecnicamente equivalente.

O produto adicionalmente marcado com a letra suplementar "W" indica que o equipamento foi ensaiado em uma solução saturada a 5% de NaCl p/p, à 35 °C, pelo tempo de 200 h e foi aprovado para uso em atmosferas salinas, condicionado à utilização de acessórios de instalação no mesmo material do equipamento e de bujões de aço inoxidável ASTM-A240, para fechamento das entradas roscadas não utilizadas. Os materiais de fabricação dos equipamentos aprovados para letra "W" são: aço inoxidável AISI 316 e alumínio Copper Free SAE 336 pintados (Procedimento P-CQ-FAB764-10) com tinta Resina Poliéster ou Resina Epoxy com espessura da camada de tinta de 70 a 150 µm e 120 a 200 µm, respectivamente, ou pintados com o plano de pintura P1 e P2 (Procedimento P-CQ-FAB-765-05) com tinta Resina Epoxy ou Poliuretano Acrílico Alifático com espessura de camada de tinta de 290 µm a 405 µm e 185 µm a 258 µm, respectivamente.

Os planos de pintura P1 e P2 são permitidos apenas para equipamento fornecido com plaqueta de identificação com marcação para grupo de gás IIB.

O grau de proteção IP68 só é garantido se nas entradas roscadas de ½" NPT for utilizado vedante não endurecível à base de silicone conforme Procedimento P-DM-FAB277-07.

O segundo numeral oito indica que o equipamento foi ensaiado para uma condição de submersão de dez metros por vinte e quatro horas. O acessório deve ser instalado em equipamentos com grau de proteção equivalente.

Este certificado é válido apenas para os produtos dos modelos avaliados. Qualquer modificação nos projetos, bem como a utilização de componentes ou materiais diferentes daqueles definidos pela documentação descritiva dos produtos, sem a prévia autorização do Cepel, invalidará este certificado.

É responsabilidade do fabricante assegurar que os produtos fornecidos ao mercado nacional estejam de acordo com as especificações e documentação descritiva avaliada, relacionadas neste certificado.

As atividades de instalação, inspeção, manutenção, reparo, revisão e recuperação dos equipamentos são de responsabilidade dos usuários e devem ser executadas de acordo com os requisitos das normas técnicas vigentes e com as recomendações do fabricante.

A marcação é executada conforme a Norma ABNT NBR IEC 60079-0:2013 e o Requisito de Avaliação da Conformidade de Equipamentos Elétricos para Atmosferas Explosivas nas Condições de Gases e Vapores Inflamáveis (RAC), e é fixada na superfície externa do equipamento, em local visível. Esta marcação é legível e durável, levando-se em conta possível corrosão química.

Normas Aplicáveis:

ABNT NBR IEC 60079-0:2013 Atmosferas explosivas - Parte 0: Equipamentos - Requisitos gerais

ABNT NBR IEC 60079-1:2016 Atmosferas explosivas - Parte 1: Proteção de equipamento por invólucro à prova de explosão "d"

ABNT NBR IEC 60079-11:2013 Atmosferas explosivas - Parte 11: Proteção de equipamento por segurança intrínseca "i"

ABNT NBR IEC 60079-26:2016 Equipamentos elétricos para atmosferas explosivas - Parte 26: Equipamentos com nível de proteção de equipamento (EPL) Ga

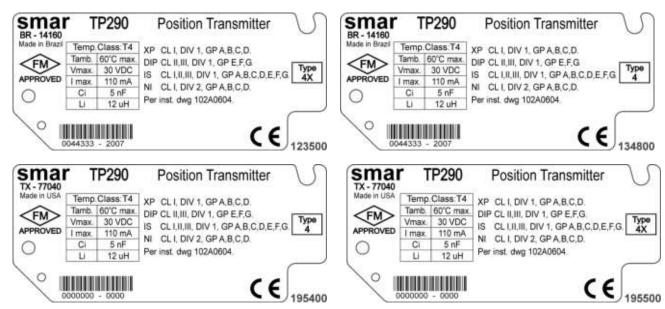
ABNT NBR IEC 60079-31:2014 Atmosferas explosivas - Parte 31: Proteção de equipamentos contra ignição de poeira por invólucros "t"

ABNT NBR IEC 60529:2017 Graus de proteção para invólucros de equipamentos elétricos (Código IP)

Desenhos 102A1377, 102A1304, 102A2062, 102A2061, 102A2096

## Identification Plates

#### **FM Approvals**



DNV GL Presafe A/S / DEKRA Testing and Certification GmbH



CEPEL (Centro de Pesquisa de Energia Elétrica)



### FM Approvals (Factory Mutual)

AZARDOUS OR DIVISION 2 AREA BAZARDOUS OR DIVISION 2 AREA SAFE AREA APPARATUS SAFE AREA ON CONTAIN UNDER SAFE AREA ON CONTAIN UNDER A A A A A A A A A A A A A A A A A A A	EA MISA RP12-6	ORDANCE TO FM→ NSULATED FROM PANELS ANCE TO EARTH MUST BE CURVE. LATE THE END NOT	AND LI MUST BE APPARATUS.	COMPONENTS CAN NOT BE SUBSTITUTED WITHOUT PREVIOUS MANUFACTURER APPROVAL.	
NON HAZARDOUS OR DIVISION 2 A SAFE AREA APPARATUS UNSPECIFIED, EXCEPT THAT IT MUST NOT BE SUPPLIED FROM, NOR CONTAIN UNDER NORMAL OR ABNORMAL CONDITIONS, A SOURCE OF POTENTIAL IN RELATION TO EARTH IN EXCESS OF 250VAC OR 250VDC. POWER SUPPLY A SOURCE OF POTENTIAL IN RELATION TO EARTH IN EXCESS OF 250VAC OR 250VDC. POWER SUPPLY A SOURCE OF POTENTIAL IN RELATION TO EARTH IN EXCESS OF 250VAC OR 250VDC.	HAZARDOUS AREA REQUIREMENTS: 1 - INSTALLATION TO BE IN ACCORDANCE WITH ANSIVE		GROUNDED. CABLE CAPACITANCE SMALLER THAN Ca AN INTRINSICALLY SA ENTITY VALUES:		MODEL TP290 & TP301 - SERIES CLASS I,II,III DIV.1, GROUPS A,B,C,D,E,F & G ENTITY VALUES: 4-20mA CI = 50 LI = 12uH Vmax ≤ 30V Imax ≤ 110mA
FM	NON HAZARDOUS OR DIVISION 2 AREA		ASSOCIATED APPARATUS		ENTITY PARAMETERS FOR ASSOCIATED APPARATUS CLASS I,II,III DIV.1, GROUPS A,B,C,D,E,F & G Ca ≥ CABLE CAPACITANCE +5nF La ≥ CABLE CAPACITANCE +12uH 4-20mA Voc ≥ 30V Isc ≤ 110mA
APPROVED       APPROVAL CONTROLLED BY C.A.R.     DRAWN     CHECKED     PROJECT     APPROVAL       ////////////////////////////////////		MC	DACIR SINASTRE	BASÍLIO MISSAWA	

sm	ar	SRF – Service Request Form TP Position Transmitter								
				GEN	ERAL D	ΑΤΑ				
Model:										<u> </u>
Serial	TP302()									
Number:										
TAG:										
Remote Position Sensor?	Yes ( )		No ( )							
Action:	Rotary ()		Linear ( )							
Travel:	30 mm ( )		50 mm()		100 mm (	)			Other:	mm
Configuration:	Magnetic Too	ol ( )	Palm ( )	Psion (	)	PC ( )	Software	9:	Version:	
				INSTAL	LATION	DATA				
Туре:	Valve + Atu	uador ( )		Other:						
Size:										
Travel:										
Manufacturer:										<u> </u>
Model:										
				PRO	CESS D	ΑΤΑ				
Hazardous Áre Classification	Non-Classi	ified ( )	Chemical	( )	Explos	ive ( )	Other:			<u> </u>
Interference Types	Vibration (	)	Temperat	ture()	Electro	magnetic ()	Others: _			
			S	SITUATIO	N DESC	RIPTION				
				SERVICE		ESTION				
Adjustment ()		Cleanir				Maintenance	( )		Jpdate / Up-grade (	\
Other:			- · ·		eventive	Maintenance	( )	0	puale / Op-grade (	)
Other										
					NFORM	ATION				
Company:										
Contact:										<u> </u>
Title:										
Section:										
Phone:			·					Extensior	n:	<u> </u>
E-mail:								Date:	//	
		For wa	arranty or non-v	varranty re	pair, plea	se contact you	ur represen	tative.		
	Further		n about address						us.asp.	

## **Returning Materials**

Should it become necessary to return the transmitter and/or configurator to **SMAR**, simply contact our office, informing the defective instrument serial number, and return it to our factory.

In order to speed up analysis and solution of the problem, the defective item should be returned with a description of the failure observed, with as much details as possible. Other information concerning the instrument operation, such as service and process conditions, is also helpful.

Instruments returned or to be revised outside the guarantee term should be accompanied by a purchase order or a quote request.