

HIGHLIGHTS:

- 2 relay switching outputs
- 1 analog output (0(4) ... 20 mA or 0 ... 10 V ) (optional)
$\bigcirc 5$ programmable switching modes
- electrical isolated power supply for a transmitter $(24 \mathrm{~V} / 22 \mathrm{~mA})$
- serial interface, bus operation

ADDITIONAL FUNCTIONS GIR 2002 PID:

- P,I, PI, PD or PID control mode
- 3-point motorized valve control
- continuous regulating output (optional)

GIR 2002
Art. no. 600948 (standard model)
Universal displaying and regulating device with on/off-control mode

## GIR 2002 PID

Art. no. 600951 (standard model)
Universal displaying and regulating device with PID-control mode

## General:

The universal controller GIR 2002 is the ideal device for simple control systems (on/off switching, relay outputs, ...), because of its compact construction and its high ease of use. The GIR 2002 PID (basic version) supplies one control output for a 2-point-control the types of control P, I, PI, PD or PID and a second control output for on/off switching. The device can also be configured as a 3-point motorized valve controller or as controller with continuous output (optionally).
Due to the universal input and the various switching functions the controller can be optimally adapted to the requirements of the system. The structured menu navigation allows a straightforward handling and a fast adjustment of the parameters.
A LED switching position display gives information to the user about the current status of the switching outputs. The automatic self-test and diagnostic system ensures maximum operational safety and reports systems errors by conclusive error codes. The parameters are automatically saved, so that all data will be maintained even in case of a power blackout. Among others most of the Greisinger transmitters, rpm sensors and flow rate sensors can be connected directly to the integrated transmitter power supply ( $24 \mathrm{VDC} / 22 \mathrm{~mA}$ ) of the controller.
If the device is used as a thermocouple or resistance thermometer, the measuring value can be alternatively displayed in ${ }^{\circ} \mathrm{C}$ or ${ }^{\circ} \mathrm{F}$. By means of an offset correction the measured value can be scaled i.e. to the resistivity of the wires. The current and voltage inputs can be arbitrarily scaled in the range of -1999 ... +9999.
The GIR 2002 has a serial, bus-compatible interface by default, by which a comfortable adjustment of the parameters as well as recording of measured values is possible. With the optionally available Windows library EASYBUS. dll up to 240 devices can be integrated into own programs (i.e. LabView).

## Application:

- process regulating
- temperature controller
- pressure monitoring
- rotation speed display
- flow counter, etc

Specifications:

Measuring input: Measuring / display ranges: | Accuracy |
| :--- |
| (at nominal temperature): |

## Thermocouples (4 measurings / s)

| FeCu-Ni: <br> (Type J, IEC 584) | $\begin{aligned} & -70.0 \ldots+300.0^{\circ} \mathrm{C} \text { or } \\ & -170 \ldots+950^{\circ} \mathrm{C} \end{aligned}$ | $<0.3 \% \mathrm{FS} \pm 1$ digit * |
| :---: | :---: | :---: |
| NiCr-Ni: <br> (Type K, IEC 584) | $\begin{aligned} & -70.0 \ldots+250.0^{\circ} \mathrm{C} \text { or } \\ & -270 \ldots+1372^{\circ} \mathrm{C} \end{aligned}$ | $<0.3 \% \mathrm{FS} \pm 1$ digit * |
| NiCrSi-NiSi: (Type N, IEC 584) | $\begin{aligned} & -100.0 \ldots+300.0^{\circ} \mathrm{C} \text { or } \\ & -270 \ldots+1350^{\circ} \mathrm{C} \end{aligned}$ | $<0.3 \% \mathrm{FS} \pm 1$ digit * |
| Pt10Rh-Pt: <br> (Type S, IEC 584) | $-50 \ldots+1750^{\circ} \mathrm{C}$ | $<0.5 \% \mathrm{FS} \pm 1$ digit * |
| Cu-CuNi: <br> (Type T, IEC 584) | $\begin{aligned} & -70.0 \ldots+200.0^{\circ} \mathrm{C} \text { or } \\ & -270 \ldots+400^{\circ} \mathrm{C} \end{aligned}$ | $<0.3 \% \mathrm{FS} \pm 1$ digit * |
|  | * $=$ Point of comparison: $\pm 1{ }^{\circ} \mathrm{C}$ |  |
| Resistance thermometer ( 4 measurings / s) |  |  |
| Pt 100: <br> (3-wire, DIN EN 60751) | $\begin{aligned} & -50.0 \ldots+200.0^{\circ} \mathrm{C} \text { or } \\ & -200 \ldots+850^{\circ} \mathrm{C} \end{aligned}$ | $<0.3 \% \mathrm{FS} \pm 1$ digit |
| Pt1000: <br> (2-wire, DIN EN 60751) | $-200 . . .+850^{\circ} \mathrm{C}$ | $<0.3 \% \mathrm{FS} \pm 1$ digit |

Action signals / normalized signal ( 100 measurings / s)

| $\begin{aligned} & 0 . .11 \text { V, } 0 . . .2 \text { V, } \\ & 0 . . .10 \text { V: } \end{aligned}$ | -1999 ... +9999 digit, scale freely adjustable | $<0.2 \% \mathrm{FS} \pm 1$ digit |
| :---: | :---: | :---: |
| 0 ... $20 \mathrm{~mA}, 4$... 20 mA : | -1999 ... +9999 digit, scale freely adjustable | $<0.2$ \% FS $\pm 1$ digit |
| $0 . . .50 \mathrm{mV}$ : | -1999 ... +9999 digit, scale freely adjustable | $<0.3 \% \mathrm{FS} \pm 1$ digit |
| Frequency |  |  |
| TTL-Signal: | $0.000 \text { Hz ... } 10 \text { kHz, }$ <br> scale freely adjustable | $<0.1 \%$ FS $\pm 1$ digit |
| Switching contact NPN: | $0.000 \mathrm{~Hz} \ldots 3 \mathrm{kHz},$ <br> scale freely adjustable | $<0.1 \% \mathrm{FS} \pm 1$ digit |
| Switching contact PNP: | $0.000 \mathrm{~Hz} \ldots 1 \mathrm{kHz},$ <br> scale freely adjustable | $<0.1 \% \mathrm{FS} \pm 1$ digit |
| Rotational speed: | 0.000 ... $9999 \mathrm{U} / \mathrm{min}$. | selectable prescaler: 1 ... 1000, pulse frequency: max. 600.000 Imp./min. at TTL |
| Flow: | $\begin{aligned} & 0 . . .9999 \mathrm{l} / \mathrm{s}, 0 . . .9999 \mathrm{l} / \mathrm{min} \text { or } \\ & 0 . . .9999 \mathrm{l} \text { /h } \end{aligned}$ |  |
| Counter up / down |  |  |
| TTL-signal, switching contact (NPN, PNP): | $\begin{aligned} & 0 . . .9999 \text { or } 0 \text {... } 999000 \\ & \text { (with prescaler) } \\ & \text { selectable prescaler: } 1 \text {... 1000, } \\ & \text { pulse frequency: } \\ & \text { max. } 10.000 \text { Imp./s at TTL } \end{aligned}$ | $<0.1 \% \mathrm{FS} \pm 1$ digit |
| Serial interface: | displaying and controlling from interface | alues coming via the serial |
| Outputs: Please note: Not all options are available for both device types and not all options can be combined with each other. Please see therefore the matrix on next page. |  |  |
| Output 1 R1: (standard version) | voltage free relay output (stand switching power: 5 A (ohmic lo | ard) normally-open contact, <br> d), 250 V AC |
| Optional: | H1: control output for semicon AA1: freely scalable analog out AV1: 0 ... 10V SA1: continuous output 0(4) ... SV1:0 ... 10 V | ductor relay ( $6 \mathrm{~V} \mathrm{DC} / 15 \mathrm{~mA}$ ) put 0(4)-20 mA $20 \mathrm{~mA}$ |
| Output 2 R2: <br> (standard version) | voltage free relay output (stan switching power: 10 A (ohmic | ard) change-over contact, <br> oad), 250 V AC |
| Optional: | H2: control output for semicond | ductor relay (6V DC/ 15 mA ) |
| Output 3: (not available at standard device type) |  |  |
| Optional: | R3: voltage free relay output (chance-over contact) switching power: $1 \mathrm{~A} / 40 \mathrm{~V} \mathrm{AC}$ or 30 V DC H 3 : control output for semiconductor relay ( $14 \mathrm{VDC} / 15 \mathrm{~mA}$ ) N3: electrical isolated NPN-switching contact (max. 1 A/30VDC) <br> AA3: freely scalable analog output 0(4) ... 20 mA AV3: $0 . . .10 \mathrm{~V}$ <br> SA3: continuous output 0(4) ... 20 mA <br> SV3: continuous output 0 ... 10V |  |
| Controller states: | 5 or 6, selectable (e.g. 2-point regulator, 3-point regulator, ...) |  |
| Switching point, hysteresis: | freely adjustable |  |
| Response time: | $\leq 25 \mathrm{~ms}$ at normalized signals $\leq 0.5 \mathrm{~s}$ at temperature and frequency |  |
| Display: | approx. 13 mm high, 4-digit red LED-display |  |
| Interface: | serial interface, electrical isolated, EASYBus compatible |  |
| Power supply for sensor: | $24 \mathrm{VDC} \pm 2 \%, 22 \mathrm{~mA}$ at 230 V AC power supply <br> $18 \mathrm{VDC} \pm 2 \%, 22 \mathrm{~mA}$ at 12 V DC or 24 V DC power supply |  |

